# Semi-braces and the Yang-Baxter equation

Paola Stefanelli



Università del Salento

Young Researchers Algebra Conference 2017 Napoli - May 23, 2017

### Yang-Baxter operators

The Yang-Baxter equation is a basic equation of the statistical mechanics that arose from Yang's work in 1967 and Baxter's one in 1972.

### Yang-Baxter operators

The Yang-Baxter equation is a basic equation of the statistical mechanics that arose from Yang's work in 1967 and Baxter's one in 1972.

Let V be a vector space over a field F. If  $R: V \otimes V \to V \otimes V$  is a linear map, set

### Yang-Baxter operators

The Yang-Baxter equation is a basic equation of the statistical mechanics that arose from Yang's work in 1967 and Baxter's one in 1972.

Let V be a vector space over a field F. If  $R: V \otimes V \to V \otimes V$  is a linear map, set

 $R_{12} = R \otimes id_V$ 

### Yang-Baxter operators

The Yang-Baxter equation is a basic equation of the statistical mechanics that arose from Yang's work in 1967 and Baxter's one in 1972.

Let V be a vector space over a field F. If  $R: V \otimes V \to V \otimes V$  is a linear map, set

 $R_{12} = R \otimes id_V$   $R_{23} = id_V \otimes R$ 

### Yang-Baxter operators

The Yang-Baxter equation is a basic equation of the statistical mechanics that arose from Yang's work in 1967 and Baxter's one in 1972.

Let V be a vector space over a field F. If  $R: V \otimes V \to V \otimes V$  is a linear map, set

$$R_{12} = R \otimes id_V \quad R_{23} = id_V \otimes R \quad R_{13} = (id_V \otimes \tau) (R \otimes id_V) (id_V \otimes \tau)$$

where  $\tau : V \otimes V \to V \otimes V$  is the *twist operator* given by  $\tau (u \otimes v) = v \otimes u$ .

### Yang-Baxter operators

The Yang-Baxter equation is a basic equation of the statistical mechanics that arose from Yang's work in 1967 and Baxter's one in 1972.

Let V be a vector space over a field F. If  $R: V \otimes V \to V \otimes V$  is a linear map, set

$$\textit{R}_{12} = \textit{R} \otimes \textit{id}_{\textit{V}} \quad \textit{R}_{23} = \textit{id}_{\textit{V}} \otimes \textit{R} \quad \textit{R}_{13} = (\textit{id}_{\textit{V}} \otimes \tau) (\textit{R} \otimes \textit{id}_{\textit{V}}) (\textit{id}_{\textit{V}} \otimes \tau)$$

where  $\tau: V \otimes V \to V \otimes V$  is the *twist operator* given by  $\tau(u \otimes v) = v \otimes u$ .

#### Definition

A linear map  $R: V \otimes V \longrightarrow V \otimes V$  is called a Yang-Baxter operator if it is a solution of the quantum Yang-Baxter equation, i.e.,

$$R_{12}R_{13}R_{23} = R_{23}R_{13}R_{12} \tag{1}$$

holds in the monoid of the linear maps of  $V \otimes V \otimes V$  in itself.

The Yang-Baxter equation Solutions related to semi-braces Solutions of the Yang-Baxter equation An overview of solutions of the YBE

# Set-theoretic solutions of the quantum Yang-Baxter equation

In 1992 Drinfeld suggested to study a simplified case

The Yang-Baxter equation Solutions related to semi-braces Solutions of the Yang-Baxter equation An overview of solutions of the YBE

### Set-theoretic solutions of the quantum Yang-Baxter equation

In 1992 Drinfeld suggested to study a simplified case: fixed a basis B on a vector space V we may find all solutions R induced by a linear extension of mappings  $\mathcal{R} : B \times B \to B \times B$ .

Set-theoretic solutions of the quantum Yang-Baxter equation

In 1992 Drinfeld suggested to study a simplified case: fixed a basis B on a vector space V we may find all solutions R induced by a linear extension of mappings  $\mathcal{R} : B \times B \to B \times B$ .

In particular, the following result is useful:

#### Proposition

If B is a non-empty set, denoted by  $\tau : B \times B \to B \times B$  the twist map, i.e.,  $\tau (x, y) = (y, x)$ , we have that  $\mathcal{R} : B \times B \to B \times B$  is a Yang-Baxter map if and only if the function  $r := \tau \mathcal{R} : B \times B \to B \times B$  satisfies the braid equation

$$r_1r_2r_1 = r_2r_1r_2$$

where  $r_1 := r \times id_B$  and  $r_2 := id_B \times r$ .

(2)

Set-theoretic solutions of the quantum Yang-Baxter equation

In 1992 Drinfeld suggested to study a simplified case: fixed a basis B on a vector space V we may find all solutions R induced by a linear extension of mappings  $\mathcal{R} : B \times B \to B \times B$ .

In particular, the following result is useful:

#### Proposition

If B is a non-empty set, denoted by  $\tau : B \times B \to B \times B$  the twist map, i.e.,  $\tau (x, y) = (y, x)$ , we have that  $\mathcal{R} : B \times B \to B \times B$  is a Yang-Baxter map if and only if the function  $r := \tau \mathcal{R} : B \times B \to B \times B$  satisfies the braid equation

$$r_1r_2r_1 = r_2r_1r_2$$

where  $r_1 := r \times id_B$  and  $r_2 := id_B \times r$ .

Usually, r or  $\mathcal{R}$  is called a set-theoretic solution of the quantum Yang-Baxter equation.

(2)

The Yang-Baxter equation Solutions related to semi-braces Solutions of the Yang-Baxter equation An overview of solutions of the YBE

Some classes of set-theoretic solutions

Question: How to obtain set-theoretic solutions of the Yang-Baxter equation?

**Question**: How to obtain set-theoretic solutions of the Yang-Baxter equation? Determining all set-theoretic solutions of the Yang-Baxter equation is a very difficult task. Even if we may find several works about this topic, it is still an open problem.

**Question**: How to obtain set-theoretic solutions of the Yang-Baxter equation? Determining all set-theoretic solutions of the Yang-Baxter equation is a very difficult task. Even if we may find several works about this topic, it is still an open problem.

We have different classes of solutions that are studied.

Question: How to obtain set-theoretic solutions of the Yang-Baxter equation?

Determining all set-theoretic solutions of the Yang-Baxter equation is a very difficult task. Even if we may find several works about this topic, it is still an open problem.

We have different classes of solutions that are studied.

#### Definition

Question: How to obtain set-theoretic solutions of the Yang-Baxter equation?

Determining all set-theoretic solutions of the Yang-Baxter equation is a very difficult task. Even if we may find several works about this topic, it is still an open problem.

We have different classes of solutions that are studied.

#### Definition

Let B be a set,  $\lambda_x$ ,  $\rho_y : B \times B \to B \times B$  and  $r : B \times B \to B \times B$  defined by  $r(x, y) = (\lambda_x(y), \rho_y(x))$  that satisfies the braid equation. Then the solution r is said to be

- left non-degenerate if  $\lambda_x$  is bijective, for every  $x \in B$ ;

Question: How to obtain set-theoretic solutions of the Yang-Baxter equation?

Determining all set-theoretic solutions of the Yang-Baxter equation is a very difficult task. Even if we may find several works about this topic, it is still an open problem.

We have different classes of solutions that are studied.

#### Definition

- left non-degenerate if  $\lambda_x$  is bijective, for every  $x \in B$ ;
- **right non-degenerate** if  $\rho_y$  is bijective, for every  $y \in B$ ;

Question: How to obtain set-theoretic solutions of the Yang-Baxter equation?

Determining all set-theoretic solutions of the Yang-Baxter equation is a very difficult task. Even if we may find several works about this topic, it is still an open problem.

We have different classes of solutions that are studied.

#### Definition

- left non-degenerate if  $\lambda_x$  is bijective, for every  $x \in B$ ;
- **right non-degenerate** if  $\rho_y$  is bijective, for every  $y \in B$ ;
- **non-degenerate** if r is both left and right non-degenerate;

Question: How to obtain set-theoretic solutions of the Yang-Baxter equation?

Determining all set-theoretic solutions of the Yang-Baxter equation is a very difficult task. Even if we may find several works about this topic, it is still an open problem.

We have different classes of solutions that are studied.

#### Definition

- left non-degenerate if  $\lambda_x$  is bijective, for every  $x \in B$ ;
- **right non-degenerate** if  $\rho_y$  is bijective, for every  $y \in B$ ;
- **non-degenerate** if r is both left and right non-degenerate;
- **involutive** if  $r^2 = id_{B \times B}$ ;

Question: How to obtain set-theoretic solutions of the Yang-Baxter equation?

Determining all set-theoretic solutions of the Yang-Baxter equation is a very difficult task. Even if we may find several works about this topic, it is still an open problem.

We have different classes of solutions that are studied.

#### Definition

- left non-degenerate if  $\lambda_x$  is bijective, for every  $x \in B$ ;
- **right non-degenerate** if  $\rho_y$  is bijective, for every  $y \in B$ ;
- **non-degenerate** if r is both left and right non-degenerate;
- involutive if  $r^2 = id_{B \times B}$ ;
- idempotent if  $r^2 = r$ .

▶ [V.V. Lyubashenko] If B is a set, the function  $r : B \times B \rightarrow B \times B$  given by

$$r(x,y) = (f(y),g(x)),$$

for all  $x, y \in B$ , is a solution, where f, g are functions from B to itself such that fg = gf.

▶ [V.V. Lyubashenko] If B is a set, the function  $r : B \times B \rightarrow B \times B$  given by

$$r(x,y) = (f(y),g(x)),$$

for all  $x, y \in B$ , is a solution, where f, g are functions from B to itself such that fg = gf. We have that:

- r is left non-degenerate if and only if f is bijective;

▶ [V.V. Lyubashenko] If B is a set, the function  $r : B \times B \rightarrow B \times B$  given by

$$r(x,y) = (f(y),g(x)),$$

for all  $x, y \in B$ , is a solution, where f, g are functions from B to itself such that fg = gf. We have that:

- r is left non-degenerate if and only if f is bijective;
- r is right non-degenerate if and only if g is bijective;

▶ [V.V. Lyubashenko] If B is a set, the function  $r : B \times B \rightarrow B \times B$  given by

$$r(x,y) = (f(y),g(x)),$$

for all  $x, y \in B$ , is a solution, where f, g are functions from B to itself such that fg = gf. We have that:

- r is left non-degenerate if and only if f is bijective;
- r is right non-degenerate if and only if g is bijective;
- r is involutive if and only if f, g are bijective and  $g = f^{-1}$ ;

▶ [V.V. Lyubashenko] If B is a set, the function  $r : B \times B \rightarrow B \times B$  given by

$$r(x,y) = (f(y),g(x)),$$

for all  $x, y \in B$ , is a solution, where f, g are functions from B to itself such that fg = gf. We have that:

- r is left non-degenerate if and only if f is bijective;
- r is right non-degenerate if and only if g is bijective;
- r is involutive if and only if f, g are bijective and  $g = f^{-1}$ ;

▷ If  $f = g = id_B$ , then r(x, y) = (y, x), i.e., r is the *twist* map. In particular r is non-degenerate and also involutive.

▶ [V.V. Lyubashenko] If B is a set, the function  $r : B \times B \rightarrow B \times B$  given by

$$r(x,y) = (f(y),g(x)),$$

for all  $x, y \in B$ , is a solution, where f, g are functions from B to itself such that fg = gf. We have that:

- r is left non-degenerate if and only if f is bijective;
- r is right non-degenerate if and only if g is bijective;
- r is involutive if and only if f, g are bijective and  $g = f^{-1}$ ;

▷ If  $f = g = id_B$ , then r(x, y) = (y, x), i.e., r is the *twist* map. In particular r is non-degenerate and also involutive.

▷ If we fix  $c \in B$  and consider  $f : B \to B$  defined by f(x) = c, for every  $x \in B$ , and g = f, then we obtain r(x, y) = (c, c), for all  $x, y \in B$ .

▶ [V.V. Lyubashenko] If B is a set, the function  $r : B \times B \rightarrow B \times B$  given by

$$r(x,y) = (f(y),g(x)),$$

for all  $x, y \in B$ , is a solution, where f, g are functions from B to itself such that fg = gf. We have that:

- r is left non-degenerate if and only if f is bijective;
- r is right non-degenerate if and only if g is bijective;
- r is involutive if and only if f, g are bijective and  $g = f^{-1}$ ;

▷ If  $f = g = id_B$ , then r(x, y) = (y, x), i.e., r is the *twist* map. In particular r is non-degenerate and also involutive.

▷ If we fix  $c \in B$  and consider  $f : B \to B$  defined by f(x) = c, for every  $x \in B$ , and g = f, then we obtain r(x, y) = (c, c), for all  $x, y \in B$ . Clearly, r is degenerate

▶ [V.V. Lyubashenko] If B is a set, the function  $r : B \times B \rightarrow B \times B$  given by

$$r(x,y) = (f(y),g(x)),$$

for all  $x, y \in B$ , is a solution, where f, g are functions from B to itself such that fg = gf. We have that:

- r is left non-degenerate if and only if f is bijective;
- r is right non-degenerate if and only if g is bijective;
- r is involutive if and only if f, g are bijective and  $g = f^{-1}$ ;

▷ If  $f = g = id_B$ , then r(x, y) = (y, x), i.e., r is the *twist* map. In particular r is non-degenerate and also involutive.

▷ If we fix  $c \in B$  and consider  $f : B \to B$  defined by f(x) = c, for every  $x \in B$ , and g = f, then we obtain r(x, y) = (c, c), for all  $x, y \in B$ . Clearly, r is degenerate and since

$$r^{2}(x, y) = r(c, c) = (c, c) = r(x, y),$$

for all  $x, y \in B$ , then r is idempotent.

# GU Pei solutions

▶ [GU Pei, 1997] If B is a group, the function  $r: B \times B \rightarrow B \times B$  defined by

$$r(x,y) = \left(xyf(x)^{-1}, f(x)\right)$$

for all  $x, y \in B$ , is a solution, where  $f : B \to B$  is a *metahomomorphism* of the group B,

# GU Pei solutions

▶ [GU Pei, 1997] If B is a group, the function  $r : B \times B \rightarrow B \times B$  defined by

$$r(x,y) = \left(xyf(x)^{-1}, f(x)\right)$$

for all  $x, y \in B$ , is a solution, where  $f : B \to B$  is a *metahomomorphism* of the group B, i.e., f satisfies the condition

$$f(xyf(x)^{-1}) = f(x)f(y)f^{2}(x)^{-1},$$
(3)

for all  $x, y \in B$ .

### GU Pei solutions

▶ [GU Pei, 1997] If B is a group, the function  $r : B \times B \rightarrow B \times B$  defined by

$$r(x,y) = \left(xyf(x)^{-1}, f(x)\right)$$

for all  $x, y \in B$ , is a solution, where  $f : B \to B$  is a *metahomomorphism* of the group B, i.e., f satisfies the condition

$$f(xyf(x)^{-1}) = f(x)f(y)f^{2}(x)^{-1},$$
(3)

for all  $x, y \in B$ . For instance, we may choose any endomorphism of B to obtain a solution.

▶ [GU Pei, 1997] If B is a group, the function  $r: B \times B \rightarrow B \times B$  defined by

$$r(x,y) = \left(xyf(x)^{-1}, f(x)\right)$$

for all  $x, y \in B$ , is a solution, where  $f : B \to B$  is a *metahomomorphism* of the group B, i.e., f satisfies the condition

$$f(xyf(x)^{-1}) = f(x)f(y)f^{2}(x)^{-1},$$
(3)

for all  $x, y \in B$ . For instance, we may choose any endomorphism of B to obtain a solution. We may note that

- if  $x \in B$ , then  $\lambda_x(y) = xyf(x)^{-1}$ , for every  $y \in B$ , and so  $\lambda_x$  is bijective.

▶ [GU Pei, 1997] If B is a group, the function  $r: B \times B \rightarrow B \times B$  defined by

$$r(x,y) = \left(xyf(x)^{-1}, f(x)\right)$$

for all  $x, y \in B$ , is a solution, where  $f : B \to B$  is a *metahomomorphism* of the group B, i.e., f satisfies the condition

$$f(xyf(x)^{-1}) = f(x)f(y)f^{2}(x)^{-1},$$
(3)

for all  $x, y \in B$ . For instance, we may choose any endomorphism of B to obtain a solution. We may note that

- if  $x \in B$ , then  $\lambda_x(y) = xyf(x)^{-1}$ , for every  $y \in B$ , and so  $\lambda_x$  is bijective. Hence *r* is left non-degenerate; ▶ [GU Pei, 1997] If B is a group, the function  $r: B \times B \rightarrow B \times B$  defined by

$$r(x,y) = \left(xyf(x)^{-1}, f(x)\right)$$

for all  $x, y \in B$ , is a solution, where  $f : B \to B$  is a *metahomomorphism* of the group B, i.e., f satisfies the condition

$$f(xyf(x)^{-1}) = f(x)f(y)f^{2}(x)^{-1},$$
(3)

for all  $x, y \in B$ . For instance, we may choose any endomorphism of B to obtain a solution. We may note that

- if  $x \in B$ , then  $\lambda_x(y) = xyf(x)^{-1}$ , for every  $y \in B$ , and so  $\lambda_x$  is bijective. Hence *r* is left non-degenerate;

- Since  $\rho_y = f$ , for every  $y \in B$ , we have that r is right non-degenerate if and only if f is bijective.

# Venkov solutions

▶ [B.B. Venkov] If B is a set, the function  $r : B \times B \rightarrow B \times B$ , defined by

$$r(x,y)=(x*y,x),$$

for all  $x, y \in B$ , is a solution where \* is a self-distributive operation on B, i.e.,

$$x * (y * z) = (x * y) * (x * z),$$
 (4)

for all  $x, y, z \in B$ .

### Venkov solutions

▶ [B.B. Venkov] If B is a set, the function  $r : B \times B \rightarrow B \times B$ , defined by

$$r(x,y)=(x*y,x),$$

for all  $x, y \in B$ , is a solution where \* is a self-distributive operation on B, i.e.,

$$x * (y * z) = (x * y) * (x * z),$$
 (4)

for all  $x, y, z \in B$ . For instance,

▷ we may choose *B* a group and  $x * y := xyx^{-1}$ , for all  $x, y \in B$ , to obtain a solution that is non-degenerate;

#### Venkov solutions

▶ [B.B. Venkov] If B is a set, the function  $r : B \times B \rightarrow B \times B$ , defined by

$$r(x,y)=(x*y,x),$$

for all  $x, y \in B$ , is a solution where \* is a self-distributive operation on B, i.e.,

$$x * (y * z) = (x * y) * (x * z),$$
 (4)

for all  $x, y, z \in B$ . For instance,

▷ we may choose *B* a group and  $x * y := xyx^{-1}$ , for all  $x, y \in B$ , to obtain a solution that is non-degenerate;

▷ we may choose on a set *B*, x \* y := x, for all  $x, y \in B$ .

#### Venkov solutions

▶ [B.B. Venkov] If B is a set, the function  $r : B \times B \rightarrow B \times B$ , defined by

$$r(x,y)=(x*y,x),$$

for all  $x, y \in B$ , is a solution where \* is a self-distributive operation on B, i.e.,

$$x * (y * z) = (x * y) * (x * z),$$
 (4)

for all  $x, y, z \in B$ . For instance,

▷ we may choose *B* a group and  $x * y := xyx^{-1}$ , for all  $x, y \in B$ , to obtain a solution that is non-degenerate;

▷ we may choose on a set B, x \* y := x, for all  $x, y \in B$ . Hence, r(x, y) = (x, x), for all  $x, y \in B$  is a right non-degenerate solution that is also idempotent.

#### Venkov solutions

▶ [B.B. Venkov] If B is a set, the function  $r : B \times B \rightarrow B \times B$ , defined by

$$r(x,y)=(x*y,x),$$

for all  $x, y \in B$ , is a solution where \* is a self-distributive operation on B, i.e.,

$$x * (y * z) = (x * y) * (x * z),$$
 (4)

for all  $x, y, z \in B$ . For instance,

▷ we may choose *B* a group and  $x * y := xyx^{-1}$ , for all  $x, y \in B$ , to obtain a solution that is non-degenerate;

▷ we may choose on a set B, x \* y := x, for all  $x, y \in B$ . Hence, r(x, y) = (x, x), for all  $x, y \in B$  is a right non-degenerate solution that is also idempotent.

Such a structure (B, \*) is called *shelf* or *self-distributive structure* and, nowadays, receives attention by some authors, as for instance Lebed and Vendramin [2017].

# Lebed solutions

▶ [Lebed, 2016] Let  $(B, \lor, \land)$  be a distributive lattice. Then the function  $r: B \times B \to B \times B$  defined by

$$r(x,y) = (x \wedge y, x \vee y),$$

for all  $x, y \in B$ , is a solution of the Yang-Baxter equation.

# Lebed solutions

▶ [Lebed, 2016] Let  $(B, \lor, \land)$  be a distributive lattice. Then the function  $r: B \times B \to B \times B$  defined by

$$r(x,y) = (x \wedge y, x \vee y),$$

for all  $x, y \in B$ , is a solution of the Yang-Baxter equation. In particular, r is neither right nor left non-degenerate ▶ [Lebed, 2016] Let  $(B, \lor, \land)$  be a distributive lattice. Then the function  $r: B \times B \to B \times B$  defined by

$$r(x,y) = (x \wedge y, x \vee y),$$

for all  $x, y \in B$ , is a solution of the Yang-Baxter equation. In particular, r is neither right nor left non-degenerate and since

$$r^{2}(x,y) = r(x \land y, x \lor y) = ((x \land y) \land (x \lor y), (x \land y) \lor (x \lor y))$$
$$= (x \land y, x \lor y) = r(x,y),$$

for all  $x, y \in B$ , then r is idempotent.

The Yang-Baxter equation Solutions related to semi-braces Solutions of the Yang-Baxter equation An overview of solutions of the YBE

# A very brief state of the art

In the last years several approaches have been suggested in many works.

# A very brief state of the art

In the last years several approaches have been suggested in many works.

In 1999 Etingof, Schedler and Soloviev, and Gateva-Ivanova and Van den Bergh laid the groundwork for the study of the *non-degenerate involutive* solutions, mainly in group theory terms.

# A very brief state of the art

In the last years several approaches have been suggested in many works.

In 1999 Etingof, Schedler and Soloviev, and Gateva-Ivanova and Van den Bergh laid the groundwork for the study of the *non-degenerate involutive* solutions, mainly in group theory terms. Many results are obtained for this class by several author, such as Rump, Cedó, Jespers, Okniński and Smoktunowicz.

In 1999 Etingof, Schedler and Soloviev, and Gateva-Ivanova and Van den Bergh laid the groundwork for the study of the *non-degenerate involutive* solutions, mainly in group theory terms. Many results are obtained for this class by several author, such as Rump, Cedó, Jespers, Okniński and Smoktunowicz.

In 2000 Lu, Yan and Zhu and independently Soloviev started to study non-degenerate solutions not necessarily involutive. In 2017 Guarnieri and Vendramin obtained new results.

In 1999 Etingof, Schedler and Soloviev, and Gateva-Ivanova and Van den Bergh laid the groundwork for the study of the *non-degenerate involutive* solutions, mainly in group theory terms. Many results are obtained for this class by several author, such as Rump, Cedó, Jespers, Okniński and Smoktunowicz.

In 2000 Lu, Yan and Zhu and independently Soloviev started to study non-degenerate solutions not necessarily involutive. In 2017 Guarnieri and Vendramin obtained new results.

Currently, some authors are interested in finding **degenerate solutions** and **idempotent solutions** such as, for instance, Lebed and Vendramin.

In 1999 Etingof, Schedler and Soloviev, and Gateva-Ivanova and Van den Bergh laid the groundwork for the study of the *non-degenerate involutive* solutions, mainly in group theory terms. Many results are obtained for this class by several author, such as Rump, Cedó, Jespers, Okniński and Smoktunowicz.

In 2000 Lu, Yan and Zhu and independently Soloviev started to study non-degenerate solutions not necessarily involutive. In 2017 Guarnieri and Vendramin obtained new results.

Currently, some authors are interested in finding **degenerate solutions** and **idempotent solutions** such as, for instance, Lebed and Vendramin.

We will focus on solutions that are only **left non-degenerate**. In particular, we will show how to determine such solutions through a new structure, the **semi-brace**.

In 1999 Etingof, Schedler and Soloviev, and Gateva-Ivanova and Van den Bergh laid the groundwork for the study of the *non-degenerate involutive* solutions, mainly in group theory terms. Many results are obtained for this class by several author, such as Rump, Cedó, Jespers, Okniński and Smoktunowicz.

In 2000 Lu, Yan and Zhu and independently Soloviev started to study non-degenerate solutions not necessarily involutive. In 2017 Guarnieri and Vendramin obtained new results.

Currently, some authors are interested in finding **degenerate solutions** and **idempotent solutions** such as, for instance, Lebed and Vendramin.

We will focus on solutions that are only **left non-degenerate**. In particular, we will show how to determine such solutions through a new structure, the **semi-brace**. We will see that we obtain also **idempotent** solutions.

In [Semi-braces and the Yang-Baxter equation, J. Algebra **483** (2017), 163–187], F. Catino, I. Colazzo and myself introduce the *semi-brace*, a structure that allows us to obtain new solutions of the Yang-Baxter equation.

In [Semi-braces and the Yang-Baxter equation, J. Algebra **483** (2017), 163–187], F. Catino, I. Colazzo and myself introduce the *semi-brace*, a structure that allows us to obtain new solutions of the Yang-Baxter equation.

#### Definition

A set B with two operations + and  $\circ$  is a (left) semi-brace if (B, +) is a left cancellative semigroup,  $(B, \circ)$  is a group and

$$a \circ (b+c) = a \circ b + a \circ (a^{-} + c)$$
(5)

holds for all a, b,  $c \in B$ , where by  $a^-$  we denote the inverse of the element a with respect to  $\circ$ .

The Yang-Baxter equation Solutions related to semi-braces The solution associated to a semi-brace Solutions obtained by quotient structures

#### How to obtain a solution through a semi-brace

Theorem (Catino, Colazzo, P.S., J. Algebra, 2017)

Let B be a semi-brace. Then, the function  $r : B \times B \rightarrow B \times B$  given by

$$r(a,b) = \left(a \circ (a^{-} + b), (a^{-} + b)^{-} \circ b\right)$$
(6)

for all  $a, b \in B$ , is a left non-degenerate solution of the Yang-Baxter equation.

# How to obtain a solution through a semi-brace

Theorem (Catino, Colazzo, P.S., J. Algebra, 2017)

Let B be a semi-brace. Then, the function  $r:B\times B\to B\times B$  given by

$$r(a,b) = \left(a \circ (a^{-} + b), (a^{-} + b)^{-} \circ b\right)$$
(6)

for all  $a, b \in B$ , is a left non-degenerate solution of the Yang-Baxter equation. We call r the solution associated to the semi-brace B.

# How to obtain a solution through a semi-brace

Theorem (Catino, Colazzo, P.S., J. Algebra, 2017)

Let B be a semi-brace. Then, the function  $r:B\times B\to B\times B$  given by

$$r(a,b) = \left(a \circ (a^{-} + b), (a^{-} + b)^{-} \circ b\right)$$
(6)

for all  $a, b \in B$ , is a left non-degenerate solution of the Yang-Baxter equation. We call r the solution associated to the semi-brace B.

In fact, if B is a semi-brace,

# How to obtain a solution through a semi-brace

Theorem (Catino, Colazzo, P.S., J. Algebra, 2017)

Let B be a semi-brace. Then, the function  $r:B\times B\to B\times B$  given by

$$r(a,b) = \left(a \circ (a^{-} + b), (a^{-} + b)^{-} \circ b\right)$$
(6)

for all  $a, b \in B$ , is a left non-degenerate solution of the Yang-Baxter equation. We call r the solution associated to the semi-brace B.

In fact, if B is a semi-brace,

 the function λ<sub>a</sub> : B → B defined by λ<sub>a</sub> (b) = a ∘ (a<sup>-</sup> + b) is bijective, for every a ∈ B;

# How to obtain a solution through a semi-brace

Theorem (Catino, Colazzo, P.S., J. Algebra, 2017)

Let B be a semi-brace. Then, the function  $r:B\times B\to B\times B$  given by

$$r(a,b) = \left(a \circ (a^{-} + b), (a^{-} + b)^{-} \circ b\right)$$
(6)

for all  $a, b \in B$ , is a left non-degenerate solution of the Yang-Baxter equation. We call r the solution associated to the semi-brace B.

In fact, if B is a semi-brace,

- the function λ<sub>a</sub> : B → B defined by λ<sub>a</sub> (b) = a ∘ (a<sup>-</sup> + b) is bijective, for every a ∈ B;
- the function ρ<sub>b</sub>: B → B defined by ρ<sub>b</sub>(a) = (a<sup>-</sup> + b)<sup>-</sup> ∘ b is not bijective, for every b ∈ B, if the additive structure (B, +) is not a group.

# How to obtain a solution through a semi-brace

Theorem (Catino, Colazzo, P.S., J. Algebra, 2017)

Let B be a semi-brace. Then, the function  $r:B\times B\to B\times B$  given by

$$r(a,b) = \left(a \circ (a^{-} + b), (a^{-} + b)^{-} \circ b\right)$$
(6)

for all  $a, b \in B$ , is a left non-degenerate solution of the Yang-Baxter equation. We call r the solution associated to the semi-brace B.

In fact, if B is a semi-brace,

- the function λ<sub>a</sub> : B → B defined by λ<sub>a</sub> (b) = a ∘ (a<sup>-</sup> + b) is bijective, for every a ∈ B;
- the function ρ<sub>b</sub>: B → B defined by ρ<sub>b</sub>(a) = (a<sup>-</sup> + b)<sup>-</sup> ∘ b is not bijective, for every b ∈ B, if the additive structure (B, +) is not a group.

# How to obtain a solution through a semi-brace

Theorem (Catino, Colazzo, P.S., J. Algebra, 2017)

Let B be a semi-brace. Then, the function  $r:B\times B\to B\times B$  given by

$$r(a,b) = \left(a \circ (a^{-} + b), (a^{-} + b)^{-} \circ b\right)$$
(6)

for all  $a, b \in B$ , is a left non-degenerate solution of the Yang-Baxter equation. We call r the solution associated to the semi-brace B.

In fact, if B is a semi-brace,

- the function λ<sub>a</sub> : B → B defined by λ<sub>a</sub> (b) = a ∘ (a<sup>-</sup> + b) is bijective, for every a ∈ B;
- the function ρ<sub>b</sub>: B → B defined by ρ<sub>b</sub>(a) = (a<sup>-</sup> + b)<sup>-</sup> ∘ b is not bijective, for every b ∈ B, if the additive structure (B, +) is not a group.

Therefore, every solution associated to a semi-brace B that is not a skew brace is left non-degenerate and right degenerate.

# How to obtain a solution through a semi-brace

Theorem (Catino, Colazzo, P.S., J. Algebra, 2017)

Let B be a semi-brace. Then, the function  $r:B\times B\to B\times B$  given by

$$r(a,b) = \left(a \circ (a^{-} + b), (a^{-} + b)^{-} \circ b\right)$$
(6)

for all  $a, b \in B$ , is a left non-degenerate solution of the Yang-Baxter equation. We call r the solution associated to the semi-brace B.

In fact, if B is a semi-brace,

- the function λ<sub>a</sub> : B → B defined by λ<sub>a</sub> (b) = a ∘ (a<sup>-</sup> + b) is bijective, for every a ∈ B;
- the function ρ<sub>b</sub>: B → B defined by ρ<sub>b</sub>(a) = (a<sup>-</sup> + b)<sup>-</sup> ∘ b is not bijective, for every b ∈ B, if the additive structure (B, +) is not a group.

Therefore, every solution associated to a semi-brace B that is not a skew brace is left non-degenerate and right degenerate. Clearly, this solution is not bijective.

The Yang-Baxter equation Solutions related to semi-braces The solution associated to a semi-brace Solutions obtained by quotient structures

#### Example

Let  $(B, \circ)$  be a group, f an endomorphism of  $(B, \circ)$  such that  $f^2 = f$  and  $(B, +, \circ)$  the semi-brace where  $a + b = b \circ f(a)$ , for all  $a, b \in B$ .

Let  $(B, \circ)$  be a group, f an endomorphism of  $(B, \circ)$  such that  $f^2 = f$  and  $(B, +, \circ)$  the semi-brace where  $a + b = b \circ f(a)$ , for all  $a, b \in B$ . Then, if  $a, b \in B$ ,

- 
$$\lambda_a(b) = a \circ (a^- + b) = a \circ b \circ f(a)^-;$$

Let  $(B, \circ)$  be a group, f an endomorphism of  $(B, \circ)$  such that  $f^2 = f$  and  $(B, +, \circ)$  the semi-brace where  $a + b = b \circ f(a)$ , for all  $a, b \in B$ . Then, if  $a, b \in B$ ,

- 
$$\lambda_a(b) = a \circ (a^- + b) = a \circ b \circ f(a)^-;$$

- 
$$ho_b(a) = \left(a^- + b\right)^- \circ b = f(a);$$

Let  $(B, \circ)$  be a group, f an endomorphism of  $(B, \circ)$  such that  $f^2 = f$  and  $(B, +, \circ)$  the semi-brace where  $a + b = b \circ f(a)$ , for all  $a, b \in B$ . Then, if  $a, b \in B$ ,

- 
$$\lambda_a(b) = a \circ (a^- + b) = a \circ b \circ f(a)^-;$$

- 
$$ho_b(a) = (a^- + b)^- \circ b = f(a);$$

Hence, the solution  $r: B \times B \rightarrow B \times B$  associated to B is given by

$$r(a,b) = (a \circ b \circ f(a)^{-}, f(a))$$
(7)

Let  $(B, \circ)$  be a group, f an endomorphism of  $(B, \circ)$  such that  $f^2 = f$  and  $(B, +, \circ)$  the semi-brace where  $a + b = b \circ f(a)$ , for all  $a, b \in B$ . Then, if  $a, b \in B$ ,

- 
$$\lambda_a(b) = a \circ (a^- + b) = a \circ b \circ f(a)^-;$$

- 
$$ho_b(a) = (a^- + b)^- \circ b = f(a);$$

Hence, the solution  $r: B \times B \rightarrow B \times B$  associated to B is given by

$$r(a,b) = (a \circ b \circ f(a)^{-}, f(a))$$
(7)

Note that r belongs to the class of GU Pei solutions.

Let  $(B, \circ)$  be a group, f an endomorphism of  $(B, \circ)$  such that  $f^2 = f$  and  $(B, +, \circ)$  the semi-brace where  $a + b = b \circ f(a)$ , for all  $a, b \in B$ . Then, if  $a, b \in B$ ,

- 
$$\lambda_a(b) = a \circ (a^- + b) = a \circ b \circ f(a)^-;$$

- 
$$ho_b(a) = (a^- + b)^- \circ b = f(a);$$

Hence, the solution  $r: B \times B \rightarrow B \times B$  associated to B is given by

$$r(a,b) = (a \circ b \circ f(a)^{-}, f(a))$$
(7)

Note that r belongs to the class of GU Pei solutions. Moreover,

▶ if  $f = id_B$ , then  $r(a, b) = (a \circ b \circ a^-, a)$ , for all  $a, b \in B$ , that is a Venkov solution;

Let  $(B, \circ)$  be a group, f an endomorphism of  $(B, \circ)$  such that  $f^2 = f$  and  $(B, +, \circ)$  the semi-brace where  $a + b = b \circ f(a)$ , for all  $a, b \in B$ . Then, if  $a, b \in B$ ,

- 
$$\lambda_a(b) = a \circ (a^- + b) = a \circ b \circ f(a)^-;$$

- 
$$ho_b(a) = (a^- + b)^- \circ b = f(a);$$

Hence, the solution  $r: B \times B \rightarrow B \times B$  associated to B is given by

$$r(a,b) = (a \circ b \circ f(a)^{-}, f(a))$$
(7)

Note that r belongs to the class of GU Pei solutions. Moreover,

- ▶ if  $f = id_B$ , then  $r(a, b) = (a \circ b \circ a^-, a)$ , for all  $a, b \in B$ , that is a Venkov solution;
- ▶ if f is the null function, then  $r(a, b) = (a \circ b, 0)$ , for all  $a, b \in B$  and so, in particular, the second projection of r is constant.

Let  $(B, \circ)$  be a group, f an endomorphism of  $(B, \circ)$  such that  $f^2 = f$  and  $(B, +, \circ)$  the semi-brace where  $a + b = b \circ f(a)$ , for all  $a, b \in B$ . Then, if  $a, b \in B$ ,

- 
$$\lambda_a(b) = a \circ (a^- + b) = a \circ b \circ f(a)^-;$$

- 
$$\rho_b(a) = (a^- + b)^- \circ b = f(a);$$

Hence, the solution  $r: B \times B \rightarrow B \times B$  associated to B is given by

$$r(a,b) = (a \circ b \circ f(a)^{-}, f(a))$$
(7)

Note that r belongs to the class of GU Pei solutions. Moreover,

- ▶ if  $f = id_B$ , then  $r(a, b) = (a \circ b \circ a^-, a)$ , for all  $a, b \in B$ , that is a Venkov solution;
- if f is the null function, then r (a, b) = (a ∘ b, 0), for all a, b ∈ B and so, in particular, the second projection of r is constant. Moreover, if a, b ∈ B,

$$r^{2}(a,b) = r(a \circ b, 0) = (a \circ b \circ 0, 0) = (a \circ b, 0) = r(a,b)$$

and so r is idempotent.

#### The solution associated to a skew brace

#### Theorem (Guarnieri, Vendramin 2017)

Let  $(B, +, \circ)$  be a skew brace. Then, the function  $r : B \times B \to B \times B$  given by

$$r(a,b) = \left(\lambda_{a}(b), \lambda_{\lambda_{a}(b)}^{-1}(-a \circ b + a + a \circ b)\right)$$

for all  $a, b \in B$ , is a non-degenerate bijective solution of the Yang-Baxter equation, where if  $a \in B$ , then

$$\lambda_a(b) = -a + a \circ b,$$

for every  $b \in B$ .

#### The solution associated to a skew brace

#### Theorem (Guarnieri, Vendramin 2017)

Let  $(B, +, \circ)$  be a skew brace. Then, the function  $r : B \times B \to B \times B$  given by

$$r(a,b) = \left(\lambda_{a}(b), \lambda_{\lambda_{a}(b)}^{-1}(-a \circ b + a + a \circ b)\right)$$

for all  $a, b \in B$ , is a non-degenerate bijective solution of the Yang-Baxter equation, where if  $a \in B$ , then

$$\lambda_a(b) = -a + a \circ b,$$

for every  $b \in B$ . In particular, r is involutive if and only if B is a brace.

#### The solution associated to a skew brace

#### Theorem (Guarnieri, Vendramin 2017)

Let  $(B, +, \circ)$  be a skew brace. Then, the function  $r : B \times B \to B \times B$  given by

$$r(a,b) = \left(\lambda_{a}(b), \lambda_{\lambda_{a}(b)}^{-1}(-a \circ b + a + a \circ b)\right)$$

for all  $a, b \in B$ , is a non-degenerate bijective solution of the Yang-Baxter equation, where if  $a \in B$ , then

$$\lambda_a(b) = -a + a \circ b,$$

for every  $b \in B$ . In particular, r is involutive if and only if B is a brace.

Note that, if  $a, b \in B$ -  $\lambda_a(b) = -a + a \circ b = a \circ a^- - a + a \circ b = a \circ (a^- + b);$ 

#### The solution associated to a skew brace

#### Theorem (Guarnieri, Vendramin 2017)

Let  $(B, +, \circ)$  be a skew brace. Then, the function  $r : B \times B \to B \times B$  given by

$$r(a,b) = \left(\lambda_{a}(b), \lambda_{\lambda_{a}(b)}^{-1}(-a \circ b + a + a \circ b)\right)$$

for all  $a, b \in B$ , is a non-degenerate bijective solution of the Yang-Baxter equation, where if  $a \in B$ , then

$$\lambda_a(b) = -a + a \circ b,$$

for every  $b \in B$ . In particular, r is involutive if and only if B is a brace.

Note that, if 
$$a, b \in B$$
  
-  $\lambda_a(b) = -a + a \circ b = a \circ a^- - a + a \circ b = a \circ (a^- + b);$   
-  $\rho_b(a) = \lambda_{\lambda_a(b)}^{-1}(-a \circ b + a + a \circ b) = \lambda_{(\lambda_a(b))^-}(-(-a + a \circ b) + a \circ b)$ 

#### The solution associated to a skew brace

#### Theorem (Guarnieri, Vendramin 2017)

Let  $(B, +, \circ)$  be a skew brace. Then, the function  $r : B \times B \to B \times B$  given by

$$r(a,b) = \left(\lambda_{a}(b), \lambda_{\lambda_{a}(b)}^{-1}(-a \circ b + a + a \circ b)\right)$$

for all  $a, b \in B$ , is a non-degenerate bijective solution of the Yang-Baxter equation, where if  $a \in B$ , then

$$\lambda_a(b) = -a + a \circ b,$$

for every  $b \in B$ . In particular, r is involutive if and only if B is a brace.

Note that, if 
$$a, b \in B$$
  
 $-\lambda_a(b) = -a + a \circ b = a \circ a^- - a + a \circ b = a \circ (a^- + b);$   
 $-\rho_b(a) = \lambda_{\lambda_a(b)}^{-1}(-a \circ b + a + a \circ b) = \lambda_{(\lambda_a(b))^-}(-(-a + a \circ b) + a \circ b)$   
 $= \lambda_{(\lambda_a(b))^-}(-\lambda_a(b) + a \circ b) = (\lambda_a(b))^- \circ (\lambda_a(b) - \lambda_a(b) + a \circ b)$ 

#### Paola Stefanelli - Semi-braces and the Yang-Baxter equation

#### The solution associated to a skew brace

#### Theorem (Guarnieri, Vendramin 2017)

Let  $(B, +, \circ)$  be a skew brace. Then, the function  $r : B \times B \to B \times B$  given by

$$r(a,b) = \left(\lambda_{a}(b), \lambda_{\lambda_{a}(b)}^{-1}(-a \circ b + a + a \circ b)\right)$$

for all  $a, b \in B$ , is a non-degenerate bijective solution of the Yang-Baxter equation, where if  $a \in B$ , then

$$\lambda_a(b) = -a + a \circ b,$$

for every  $b \in B$ . In particular, r is involutive if and only if B is a brace.

Note that, if 
$$a, b \in B$$
  
 $-\lambda_a(b) = -a + a \circ b = a \circ a^- - a + a \circ b = a \circ (a^- + b);$   
 $-\rho_b(a) = \lambda_{\lambda_a(b)}^{-1}(-a \circ b + a + a \circ b) = \lambda_{(\lambda_a(b))^-}(-(-a + a \circ b) + a \circ b)$   
 $= \lambda_{(\lambda_a(b))^-}(-\lambda_a(b) + a \circ b) = (\lambda_a(b))^- \circ (\lambda_a(b) - \lambda_a(b) + a \circ b)$   
 $= (a^- + b)^- \circ a^- \circ a \circ b = (a^- + b)^- \circ b$ 

#### Paola Stefanelli - Semi-braces and the Yang-Baxter equation

#### The solution associated to a skew brace

#### Theorem (Guarnieri, Vendramin 2017)

Let  $(B, +, \circ)$  be a skew brace. Then, the function  $r : B \times B \to B \times B$  given by

$$r(a,b) = \left(\lambda_{a}(b), \lambda_{\lambda_{a}(b)}^{-1}(-a \circ b + a + a \circ b)\right)$$

for all  $a, b \in B$ , is a non-degenerate bijective solution of the Yang-Baxter equation, where if  $a \in B$ , then

$$\lambda_a(b) = -a + a \circ b,$$

for every  $b \in B$ . In particular, r is involutive if and only if B is a brace.

Note that, if 
$$a, b \in B$$
  
 $-\lambda_a(b) = -a + a \circ b = a \circ a^- - a + a \circ b = a \circ (a^- + b);$   
 $-\rho_b(a) = \lambda_{\lambda_a(b)}^{-1}(-a \circ b + a + a \circ b) = \lambda_{(\lambda_a(b))^-}(-(-a + a \circ b) + a \circ b)$   
 $= \lambda_{(\lambda_a(b))^-}(-\lambda_a(b) + a \circ b) = (\lambda_a(b))^- \circ (\lambda_a(b) - \lambda_a(b) + a \circ b)$   
 $= (a^- + b)^- \circ a^- \circ a \circ b = (a^- + b)^- \circ b$ 

Hence the solution r associated to the skew brace B is exactly the same associated to B viewed as semi-brace.

#### Paola Stefanelli - Semi-braces and the Yang-Baxter equation

## The solution associated to a brace

Theorem (Rump, 2005)

Let  $(B, +, \circ)$  be a brace. Then, the function  $r : B \times B \to B \times B$  given by

$$r(a,b) = \left( \lambda_{a}(b), \ \lambda_{\lambda_{a}(b)}^{-1}(a) 
ight)$$

is a non-degenerate involutive solution of the Yang-Baxter equation, where if  $a\in B,$  then

$$\lambda_a(b) = -a + a \circ b,$$

for every  $b \in B$ .

# The solution associated to a brace

Theorem (Rump, 2005)

Let  $(B, +, \circ)$  be a brace. Then, the function  $r : B \times B \to B \times B$  given by

$$r(a,b) = \left( \lambda_a(b), \ \lambda_{\lambda_a(b)}^{-1}(a) 
ight)$$

is a non-degenerate involutive solution of the Yang-Baxter equation, where if  $a \in B,$  then

$$\lambda_a(b) = -a + a \circ b,$$

for every  $b \in B$ .

Clearly, we may obtain this basic result as a corollary of the previous theorem by Guarnieri and Vendramin.

# The solution associated to a brace

#### Theorem (Rump, 2005)

Let  $(B, +, \circ)$  be a brace. Then, the function  $r : B \times B \to B \times B$  given by

$$r(a,b) = \left( \lambda_{a}(b), \ \lambda_{\lambda_{a}(b)}^{-1}(a) 
ight)$$

is a non-degenerate involutive solution of the Yang-Baxter equation, where if  $a\in B,$  then

$$\lambda_a(b) = -a + a \circ b,$$

for every  $b \in B$ .

Clearly, we may obtain this basic result as a corollary of the previous theorem by Guarnieri and Vendramin.

Hence the solution r associated to the brace B is exactly the same associated to B viewed as semi-brace.

Another classical way to obtain new solutions of the Yang-Baxter equation is by quotient structures and in this sense by ideals.

Another classical way to obtain new solutions of the Yang-Baxter equation is by quotient structures and in this sense by ideals. So, we introduce also a suitable concept of *ideal* of a semi-brace in order to obtain new left non-degenerate solutions of the Yang-Baxter equation through *quotient structures* of a given semi-brace.

Another classical way to obtain new solutions of the Yang-Baxter equation is by quotient structures and in this sense by ideals. So, we introduce also a suitable concept of *ideal* of a semi-brace in order to obtain new left non-degenerate solutions of the Yang-Baxter equation through *quotient structures* of a given semi-brace.

Moreover, we focus on a special ideal, the *socle* of a semi-brace, which is a generalization of that already introduced by Rump for braces and then by Guarnieri and Vendramin for skew braces.

Another classical way to obtain new solutions of the Yang-Baxter equation is by quotient structures and in this sense by ideals. So, we introduce also a suitable concept of *ideal* of a semi-brace in order to obtain new left non-degenerate solutions of the Yang-Baxter equation through *quotient structures* of a given semi-brace.

Moreover, we focus on a special ideal, the *socle* of a semi-brace, which is a generalization of that already introduced by Rump for braces and then by Guarnieri and Vendramin for skew braces.

#### Definition (Catino, Colazzo, P.S., J. Algebra, 2017)

Let B be a semi-brace. We call the set given by

$$Soc(B) = \{a \mid a \in B \mid \lambda_a = \lambda_0, \rho_a = \rho_0\}$$

the socle of the semi-brace B.

The Yang-Baxter equation Solutions related to semi-braces The solution associated to a semi-brace Solutions obtained by quotient structures

The quotient by the socle and related solution

If B is a semi-brace and consider the quotient of B by its socle Soc(B), then we may consider the solution associated to the quotient semi-brace  $\bar{S} := B/\operatorname{Soc}(B)$ 

## The quotient by the socle and related solution

If *B* is a semi-brace and consider the quotient of *B* by its socle Soc(*B*), then we may consider the solution associated to the quotient semi-brace  $\overline{S} := B/\operatorname{Soc}(B)$ , and so the function  $\tilde{r} : \overline{S} \times \overline{S} \to \overline{S} \times \overline{S}$  given by

 $\tilde{r}\left(\left[a\right],\left[b\right]\right)=\left(\left[\lambda_{a}\left(b
ight)
ight],\left[
ho_{b}\left(a
ight)
ight]
ight),$ 

for all  $a, b \in B$ , where we denote by [a] the class of the element a modulo Soc (B).

# The quotient by the socle and related solution

If *B* is a semi-brace and consider the quotient of *B* by its socle Soc(*B*), then we may consider the solution associated to the quotient semi-brace  $\overline{S} := B/\operatorname{Soc}(B)$ , and so the function  $\tilde{r} : \overline{S} \times \overline{S} \to \overline{S} \times \overline{S}$  given by

$$\tilde{r}\left(\left[a\right],\left[b\right]\right)=\left(\left[\lambda_{a}\left(b
ight)
ight],\left[
ho_{b}\left(a
ight)
ight]
ight),$$

for all  $a, b \in B$ , where we denote by [a] the class of the element a modulo Soc (B).

In this way we obtain another left non-degenerate solution other that associated to the semi-brace B.

# The quotient by the socle and related solution

If *B* is a semi-brace and consider the quotient of *B* by its socle Soc(*B*), then we may consider the solution associated to the quotient semi-brace  $\overline{S} := B/\operatorname{Soc}(B)$ , and so the function  $\tilde{r} : \overline{S} \times \overline{S} \to \overline{S} \times \overline{S}$  given by

 $\tilde{r}([a],[b]) = ([\lambda_a(b)],[\rho_b(a)]),$ 

for all  $a, b \in B$ , where we denote by [a] the class of the element a modulo Soc (B).

In this way we obtain another left non-degenerate solution other that associated to the semi-brace B.

In the classical case of an involutive non-degenerate solution, the solution  $\tilde{r}$  is the so-called retraction of r, that is widely studied by many authors as we may see, for instance, in [Rump, 2007], [Cedó, Jespers, Okniński, 2014], [Bachiller, 2015].

# Thank you for your attention!